

## Lecture 3 vectors and matrices

Open Lecture 3 on class website: [www.math.hawaii.edu/190](http://www.math.hawaii.edu/190)  
See Chapter 2 of text for detailed explanations.

Vectors are sequences of numbers.

**ROW VECTORS** Enter the following in SciLab:

`[1, 2, 3]` notation for row vectors  
`[8]= 8`  
`a=[2 3 4]` separate entries with spaces or commas  
`b=[10, 10, 10]` commas preferred, required in Fortran  
`a+b, b-a` add, subtract the respective coordinates  
`2*a, a+1` scalar product and addition  
`a^2, 2*a`  
`a*b` wrong dimensions for matrix multiplication  
`a.*b` pointwise multiplication is not matrix multiplication  
`a(1), a(2), a(3), a(i) = ith entry of vector a`  
`a($)= last, a($-1)= next to last element.`

**COLUMN VECTORS**

`a=[4; 3; 2]` notation for column vectors  
`b`  
`b'` transpose  
`b` why didn't b change?  
`b=b'`, `b` b doesn't change unless a change is assigned.  
`a+b, b-a, a.*b` operations are performed component wise.

**VECTOR OPERATIONS**

`sum(a)` sum of entries, `sum([4;3;2]) = 9`

`prod(a)` product of entries, `prod([4;3;2]) = 24`  
`max(a)` largest entry `max([4;3;2]) = 4`  
`min(a)` smallest entry `min([4;3;2]) = 2`  
`length(a)` number of entries in the vector, `length([4;3;2])=3`  
(not the geometric length or magnitude of the vector)  
`a(length(a)) = last element = a($), a(1) = first.`

**DOT (INNER) PRODUCT**

classwork problem 2.

$[a_1, a_2, \dots, a_n] \cdot [b_1, b_2, \dots, b_n] = a_1b_1 + a_2b_2 + \dots + a_nb_n$   
= the *dot product*. The `dot_product` function (built into Matlab but not Scilab) must work for vectors of any length without using "...".

**EXAMPLE E3.1** `dot_product` Write a function

`dot_product(a,b)` for the dot product of vectors `a, b`

```
function P = dot_product(a,b)
    P = sum(a.*b)
endfunction
clc; disp(dot_product([1,2],[3,4]))//Answer 11
disp(dot_product([1,2,3],[4,5,6])) //Answer 32
```

**EXAMPLE E3.2** Write a function `H(a)` for the sum of the cubes of the components of a vector `a`, i.e.,  $a_1^3 + a_2^3 + \dots + a_n^3$ . Test it on user input. Must work on vectors of any length.

```
function x=H(a)
    x=sum(a^3)
endfunction
clc
a=input('Enter a vector. > ') //try [1,2]
disp(H(a)) //on [1,2] ans. is 9
```

**MAGNITUDE (GEOMETRIC LENGTH)**  $\sqrt{a_1^2 + a_2^2 + a_3^2 + \dots + a_n^2}$

This formula only for vectors of length 3. The classwork function code below must work for vectors of any length.

**CLASSWORK c3.1(2) mag** Together. Define a function **mag(a)** which calculates the geometric length of **a**. Entering the formula one step-and-test at a time, starting with fixed input. After the function, include lines to get the vector **a** from the user and to display **mag(a)**. If you enter "[1,2,3]" you should get 3.7416574

Copy lines, File/New in SciNotes, paste, File/Save as c3.1(2)mag(a)

```
//c3.1(2)mag mag(a)=geometric length of a.
//Test on user input: a = input('Enter a vector. >')
// Entering [1, 2, 3] should give 3.7416574
//delete this line, write in the three lines for the function
```

```
clc;printf('\n')
a=input('Enter a vector.>')
disp(mag(a))
```

**MATRICES**

Enter in SciLab: -- repeat all these steps at home.

```
a=[1 2; 3 5]
b=[1,1;1,1]
```

[a,b] a followed on the right by b.

[a;b] a, with b appended below it.

2\*b,a+b, a-b, a.\*b, a\*b

[n,m]=size(a) // n= number of rows, m= number columns

a(1,2), a(2,1) a(i,j) = entry in i<sup>th</sup> row, j<sup>th</sup> column

a(2,2)=4 changes a(2,2) to 4

```
a, a(:, :)
a, a(:, 1), a(:, 2) a(:, j)= all rows of jth column= jth column
a, a(1, :), a(2, :) a(i, :)= all columns of ith row = ith row
a,
a(1, 2)=10
a(:, 2)=9
a(1, :)= [7, 8]
b
z=b saves b to z
b(1, :)= b(1, :)+2 What does this do?
b=z recovers b from z
b(:, 1)= b(:, 1)-2 What does this do?
a([2, 1], :) result of swapping rows 1, 2 //homework problem
a(:, [2, 1]) result of swapping columns 1, 2
zeros(2, 3)
ones(2, 3)
8*ones(2, 3)
```

**MATRIX MULTIPLICATION, IDENTITY MATRIX, MATRIX INVERSES**

a\*b matrix multiplication

$$\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} * \begin{bmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{bmatrix}$$

$$= \begin{bmatrix} a_{11}b_{11} + a_{12}b_{21} & a_{11}b_{12} + a_{12}b_{22} \\ a_{21}b_{11} + a_{22}b_{21} & a_{21}b_{12} + a_{22}b_{22} \end{bmatrix}$$

The entry  $a_{ij}$  in the  $i^{\text{th}}$  row and  $j^{\text{th}}$  column of the product = dot (or inner) product of the  $i^{\text{th}}$  row of the first matrix and the  $j^{\text{th}}$  column of the second matrix.

I=eye(2, 2) This is Scilab notation, Matlab uses eye(2) . I is the 2x2 identity matrix.

1 is the identity for multiplication of numbers:  $1x = x1 = x$ .

I is the identity for matrix multiplication:  $I*a = a*I = a$   
 $a, I*a, a*I,$

$x^{-1}$  is the inverse operation of multiplication of numbers:

$$x(x^{-1}) = (x^{-1})x = 1.$$

$x^{-1}$  is also the inverse operation of multiplication of matrices:

$$a * a^{-1} = a^{-1} * a = I$$

In Matlab/Scilab, the inverse  $a^{-1}$  is `inv(a)`.

```
a=[1,2;3,4]
```

```
inv(a)
```

```
a*inv(a), inv(a)*a
```

```
2.220D-16 = 2.22 × 10-16 ≈ 0
```

Computer arithmetic isn't always exact.

```
1/3 = .3333333333333333...
```

```
≈ .333333
```

**CLASSWORK C3.2(3) id** Together. Write a function `id(n)` which generates the  $n \times n$  identity matrix. Test on  $n=4, 6$ .

Copy lines, File/New in SciNotes, paste, File/Save as `c3.2(3)id`

```
//c3.2(3)id id(n)=nxn identity matrix.
```

```
//delete this line, fill in the function
```

```
clc; disp(id(3)); disp(id(4))
```

**CLASSWORK C3.3(3) add\_mult** Together. Write a function `add_mult(a,i,r,j)` which adds  $r$  times row  $j$  to row  $i$ .

Test `add_mult(a,2,8,3)` for  $a=[1,0,0;0,1,0;0,0,1]$ .

Copy lines, File/New in SciNotes, paste, File/Save as `c3.3(3)add_mult`

```
//c3.3(3)add_mult add_mult(a,i,r,j)
```

```
//delete this line, fill in the function
```

```
a=[1,0,0;0,1,0;0,0,1]; clc
```

```
disp(a); disp(add_mult(a,2,8,3))
```

**CLASSWORK PROBLEMS DUE END OF CLASS**

**c3.1(2)mag, c3.2(3)id, c3.3(3)add\_mult**

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To enable automatic routing, copy the subject line exactly.

**CLOSED-BOOK QUIZ AT BEGINNING OF CLASS** *No computer; no text.*

*Like the Hw problems. Be on time. There will be one problem. It will be like a homework problem.*

**HOMEWORK H3.1(3) distance.** The distance between points

$a = [a_1, a_2, \dots, a_n]$  and  $b = [b_1, b_2, \dots, b_n]$  is

$$\sqrt{(a_1 - b_1)^2 + (a_2 - b_2)^2 + \dots + (a_n - b_n)^2}$$

Write a Scilab function for the distance `D=distance(a,b)` between vectors  $a$  and  $b$ . Use it to find the distance between

$[1, 2]$  and  $[3, 3]$  and the distance between  $[1, 2, 3]$  and  $[3, 3, 3]$ . Your function must work for vectors of any length, it may not use `++`. See example **E3.2** above. Try entering the formula one step-and-test at a time.

```
//h3.1(3)distance Use it to find the
```

```
//distance between [1,2],[3,3] Answer: 2.23
```

```
//distance between [1,2,3],[3,3,3] Answer: 2.23
```

**HOMEWORK H3.2(3) swap** Write a Scilab function

`swap(a,i,j)` which swaps rows  $i$  and  $j$ . For example,

```

1 2 3      1 2 3
swap( 4 5 6 ,2,3)= 7 8 9
7 8 9      4 5 6

```

Fill in the blank line. See example above.

```

//h3.2(3)swap swaps rows i, j
function b=swap(a,i,j)
    b=a
    b([i,j],:)= _____
endfunction
//Testing lines
a=[1,2,3;4,5,6;7,8,9]; disp(a),disp(swap(a,1,3))
a=[3 3; 6 6]; disp(a),disp(swap(a,1,2))

```

**HOMEWORK H3.3(3) mult** Write a Scilab function `mult(a,i,r)` which multiplies row `i` by `r`. For example,

```

1 2 3      1 2 3
mult( 4 5 6 ,2,10)= 40 50 60
7 8 9      7 8 9

```

```

//h3.3(3)mult mult(a,i,r) multiplies row i by r
//test on a=[1,0,0;0,1,0;0,0,1], mult(a,2,8)

```

**HOMEWORK DUE BEFORE NEXT CLASS** Write these from scratch.

**h3.1(3)distance**, **h3.2(3)swap**, **h3.3(3)mult**

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### ELEMENTARY ROW OPERATIONS

Given a matrix, there are three types of elementary row operations: You may

- switch (permute) rows, -- `swap`
- multiply a row by a nonzero constant, -- `mult`

- add a multiple of one row to another row -- `add_mult`

To **pivot** on the  $i$ - $j$ th entry of a matrix (assumed nonzero) means using elementary row operations to make that entry 1 and all other entries in the  $j$ th column 0. The **leading coefficient** of a row is the first nonzero entry. A matrix is in **reduced row echelon form (rref)** iff the leading coefficient of each row is 1 and it is to the right of the leading coefficient of the previous row.

**CLASSWORK c4.1(3) pivot** Write a function `pivot(a,i,j)` which pivots matrix `a` on row `i` and column `j`. Assume  $a(i,j) \neq 0$ . Use a sequence of these pivots and swaps (see **h3.2(3)**) which converts `a=[0,2,3,5;2,3,4,6;5,6,6,7]` to reduced row echelon form (rref)

Copy lines, File/New in SciNotes, paste, File/Save as c4.1(3)pivot

```

//c4.1(3)pivot pivot(a,i,j) pivots on a(i,j)
//copy the code for swap here (not its testing lines).
//delete this line, fill in the function
a=[0,2,3,5;2,3,4,6;5,6,6,7]
//convert a to rref.
clc;disp(a)

```

//delete this line, add a sequence of pivots and swaps to get rref

**HOMEWORK h4.1(3) pivot** Use the classwork function `pivot(a,i,j)` to convert `a=[3,0,3,5;2,0,4,6;5,6,6,7]` to reduced row echelon form.

```

//h4.1(3)pivot add lines to convert
//a=[3,0,3,5;2,0,4,6;5,6,6,7] to rref.

```