

AN APPLICATION OF THE MULTIVARIATE LAGRANGE-BÜRMANN EXPANSION IN MATHEMATICAL GEODESY*

By

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Abstract. In the simplified model of geodesy where the earth is conceived as a rotational ellipsoid, if the eccentricity of the ellipsoid is to be determined from gravity measurements, an equation of the form $y = x - zh(x)$ is to be solved for x , where y and z are small parameters whose values can be measured and h is a known function. We obtain the expansion of x in powers of y and z by means of the general Lagrange-Bürmann formula.

1. The problem. Using the standard notations of physical geodesy,

a = major axis of the earth ellipsoid,

GM = product of the earth's mass and the gravitational constant,

J_2 = a constant in the expansion of the normal gravity
field in spherical harmonics, and

ω = angular velocity of the earth,

the equation satisfied by the eccentricity e of the ellipsoid may be stated as follows [1, 4]:

$$3J_2 = e^2 - \frac{4}{15} \frac{\omega^2 a^3}{GM} \frac{e^3}{2q_0}. \quad (1)$$

Here $2q_0$ is a known function of e ,

$$2q_0 = (1 + 3/e'^2) \arctan e' - 3/e', \quad (2)$$

where

$$e' = e/\sqrt{1 - e^2} \quad (3)$$

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is the "second eccentricity." The constants a , GM , J_2 , ω are either known or can be obtained accurately from gravity measurements. Equation (1) thus serves to obtain accurate values of e from gravity measurements. Our concern is with *solving* the equation and with exhibiting the dependence of the solution on the parameters.

The equation has the form

$$y = x - zh(x), \quad (4)$$

where

$$y = 3J_2, \quad z = \frac{\omega^2 a^3}{GM},$$

are known and $x = e^2$ is to be determined. The function

$$h(x) = \frac{4}{15} \frac{x^{3/2}}{2q_0(\sqrt{x})} \quad (5)$$

is known. In the physical problem on hand, the numerical values of y and z are both of the order of 3×10^{-3} .

2. Numerical solution of the equation. This is discussed very thoroughly in [1], and values of e are obtained that are more accurate than those given in the literature. It follows from Eq. (4) of [1] that

$$\frac{1}{h(x)} = F\left(\frac{3}{2}, \frac{3}{2}; \frac{7}{2}; x\right), \quad (6)$$

where F is the hypergeometric function. Thus h is analytic not only for $0 < x < 1$ but also at $x = 0$. Moreover, since all coefficients in the series (6) are positive, as x increases from 0 to 1, $h(x)$ decreases from $h(0) = 1$ to $h(1) = 4/15\pi$. By writing (4) as a fixed point equation,

$$x = y + zh(x), \quad (7)$$

we see that for positive y and z such that $y + z < 1$ the equation has precisely one solution, which, if z satisfies the additional condition

$$|zh'(y + z)| < 1,$$

can be found as the limit of the iteration sequence defined by $x_0 = 0$,

$$x_{n+1} = y + zh(x_n), \quad n = 0, 1, 2, \dots$$

The only numerical problem that arises is a considerable loss of accuracy, due to subtracting large numbers that are nearly equal, if h is evaluated by means of the defining relations (5) and (2). It is much preferable to compute h from the series expansion (6), which converges rapidly if x is small.

3. Analytical solution. Iteration does furnish a numerical solution of (4) for given y and z , but it does not show how this solution depends on the parameters. We therefore endeavor to find a series solution for (4). Our tool is the multidimensional Lagrange-Bürmann formula as discussed in [3]. We summarize these results briefly for convenience.

Let $\mathbf{P} = (P_1, P_2, \dots, P_n)$ be $\mathbf{x} = (x_1, x_2, \dots, x_n)$. ["Admis $c_j \neq 0$.] Let \mathbf{Q} denote the inver yields \mathbf{x} .] Let R be an arbitrar substituting \mathbf{Q} into R is given l

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Let $\mathbf{P} = (P_1, P_2, \dots, P_n)$ be an admissible system of n power series in n indeterminates $\mathbf{x} = (x_1, x_2, \dots, x_n)$. ["Admissible" means that $P_j = c_j x_j + \text{higher-order terms}$, where $c_j \neq 0$.] Let \mathbf{Q} denote the inverse system of \mathbf{P} . ["Inverse" means that \mathbf{Q} substituted into \mathbf{P} yields \mathbf{x} .] Let R be an arbitrary (single) Laurent series in \mathbf{x} . Then the series obtained by substituting \mathbf{Q} into R is given by

$$(4) \quad R \circ \mathbf{Q} = \sum_{\mathbf{k}} \text{Res}(R \mathbf{P}^{-\mathbf{k}-\mathbf{e}} \mathbf{P}') \mathbf{x}^{\mathbf{k}}, \quad (8)$$

where the summation is with respect to all index vectors $\mathbf{k} = (k_1, k_2, \dots, k_n)$, and where

$$\mathbf{x}^{\mathbf{k}} = x_1^{k_1} x_2^{k_2} \dots x_n^{k_n},$$

$$\mathbf{e} = (1, 1, \dots, 1),$$

(5) \mathbf{P}' is the Jacobian determinant of the system \mathbf{P} , and Res denotes the residue, that is, the coefficient of $\mathbf{x}^{-\mathbf{e}}$, in a Laurent series. The result (8) holds formally, that is, regardless of whether or not the series involved are convergent.

We require an application of (8), also given in [3]. Here we consider two systems of complex variables,

$$\mathbf{x} = (x_1, \dots, x_p), \quad \mathbf{y} = (y_1, \dots, y_q),$$

and a system of p functions

$$f_i(\mathbf{x}, \mathbf{y}), \quad i = 1, 2, \dots, p,$$

(6) analytic near $(\mathbf{0}, \mathbf{0})$. We write $\mathbf{f} = (f_1, \dots, f_p)$, and we denote by \mathbf{f}' the Jacobian determinant of this system with respect to the x_i , regarding the y_j as parameters. Assuming

$$\mathbf{f}(\mathbf{0}, \mathbf{0}) = \mathbf{0}, \quad \mathbf{f}'(\mathbf{0}, \mathbf{0}) \neq \mathbf{0},$$

the system of equations

$$(7) \quad \mathbf{f}(\mathbf{x}, \mathbf{y}) = \mathbf{0}$$

for sufficiently small $|\mathbf{y}|$ has precisely one solution $\mathbf{x}(\mathbf{y})$ which is analytic in \mathbf{y} and which satisfies $\mathbf{x}(\mathbf{0}) = \mathbf{0}$. We wish to find the coefficients of the power series $\mathbf{x}(\mathbf{y})$ or, more generally, of $r(\mathbf{x}(\mathbf{y}), \mathbf{y})$, where r is a given analytic function.

For a solution by means of the Lagrange-Bürmann formula we assume, without loss of generality, that the matrix

$$\left(\frac{\partial f_i}{\partial x_j}(\mathbf{0}, \mathbf{0}) \right), \quad i, j = 1, \dots, p,$$

is the identity. (This can be achieved by forming suitable linear combinations of the functions f_i and of the variables x_j .) In the power series expansion of $\mathbf{f}(\mathbf{x}, \mathbf{y})$, let $\mathbf{B}\mathbf{y}$ denote the terms that are linear in the y_j , that is,

$$\mathbf{f}(\mathbf{x}, \mathbf{y}) = \mathbf{x} + \mathbf{B}\mathbf{y} + \text{terms of degree} \geq 2.$$

(\mathbf{B} is a matrix with p rows and q columns; we think of \mathbf{y} as a column vector.) Consider the map of a $(p+q)$ -dimensional neighborhood of $(\mathbf{0}, \mathbf{0})$ defined by

$$(10) \quad \begin{pmatrix} \mathbf{u} \\ \mathbf{v} \end{pmatrix} = \begin{pmatrix} \mathbf{f}(\mathbf{x}, \mathbf{y}) - \mathbf{B}\mathbf{y} \\ \mathbf{y} \end{pmatrix}.$$

The system of $p + q$ power series representing this map near $(0, 0)$ is admissible; in fact, its Jacobian matrix at $(0, 0)$ is the identity. Hence the inverse system

$$\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x(u, v) \\ y(u, v) \end{pmatrix} \quad (11)$$

exists and can be represented by the Lagrange-Bürmann series. Letting

$$P = f(x, y) - By,$$

and noting that the Jacobian determinant of the whole system (10) is just P' , the Jacobian with respect to x , one obtains in view of $y = v$ for an arbitrary function r

$$r(x(u, v), v) = \sum_{\substack{k \in \mathbb{Z}^p \\ m \in \mathbb{Z}^q}} \text{Res}\{r(x, y)P^{-k-e}y^{-m-e}P'(x, y)\}u^k v^m. \quad (12)$$

Now evidently $f(x, y) = 0$ if and only if $u = -Bv$. Since $v = y$, the solution of (8) thus is

$$x(y) = x(-By, y),$$

and from (12) we find the explicit series expansion

$$r(x(y), y) = \sum_{\substack{k \in \mathbb{Z}^p \\ m \in \mathbb{Z}^q}} \text{Res}\{\dots\}(-By)^k y^m, \quad (13)$$

where the residues are the same as in (12).

4. Application to the geodesic equation. To apply (13) to the solution of (4), we let $p = 1, q = 2$,

$$x = (x), \quad y = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = \begin{pmatrix} y \\ z \end{pmatrix}.$$

The equation to be solved is $f(x, y) = 0$, where

$$f(x, y) = x - y - zh(x),$$

which in order to isolate first-order terms we write in the form

$$f(x, y) = x - y - z - z x g(x),$$

where

$$g(x) = \frac{1}{x}(h(x) - 1) = O(1).$$

We see that

$$By = -y - z.$$

The map (10) in our case is thus

$$\begin{pmatrix} u \\ v \end{pmatrix} = \begin{pmatrix} P \\ y \\ z \end{pmatrix}, \quad P = x(1 - zg(x)).$$

If $r(x, y) = x$, (13) now yields

$$x(y, z) = \sum_{\substack{k > 0 \\ (m, n) \in \mathbb{Z}^2}} \dots$$

and it only remains to evaluate

Since P does not depend on

we thus get

$$x(y, z) = -$$

where the residue now is taken

we may use the binomial series

where $\binom{-k}{j}$ is a binomial coefficient

$$\text{Res}_{x,z}\{x(P^{-k})'\}$$

where Res_x denotes the residue coefficients $g_k^{(n)}$ are defined by

We thus finally let

$$x(y, z) =$$

$$= j$$

If $r(\mathbf{x}, \mathbf{y}) = x$, (13) now yields

$$x(y, z) = \sum_{\substack{k > 0 \\ (m, n) \in \mathbb{Z}^2}} \text{Res} \{ x P^{-k-1} P' y^{-m-1} z^{-n-1} \} (y+z)^k y^m z^n, \quad (14)$$

and it only remains to evaluate the residues.

Since P does not depend on y , we need $m = 0$ to obtain a residue in y . Using

$$P^{-k-1} P' = -\frac{1}{k} (P^{-k})',$$

we thus get

$$x(y, z) = - \sum_{\substack{k > 0 \\ n \geq 0}} \frac{1}{k} \text{Res}_{x,z} \{ x (P^{-k})' z^{-n-1} \} (y+z)^k z^n,$$

where the residue now is taken only with respect to the variables x and z . In view of

$$P = x(1 - zg(x)),$$

we may use the binomial series to obtain

$$\begin{aligned} P^{-k} &= x^{-k} (1 - zg(x))^{-k} \\ &= x^{-k} \sum_{l=0}^{\infty} (-1)^l \binom{-k}{l} z^l g^l, \end{aligned}$$

where $\binom{-k}{l}$ is a binomial coefficient. Now for given $k > 0$ and $n \geq 0$,

$$\begin{aligned} \text{Res}_{x,z} \{ x (P^{-k})' z^{-n-1} \} &= \text{Res}_x \text{ of coefficient of } z^n \text{ in } x (P^{-k})' \\ &= -\text{Res}_x \text{ of coefficient of } z^n \text{ in } P^{-k} \\ &= -\text{coefficient of } x^{k-1} \text{ in } (-1)^n \binom{-k}{n} g^n \\ &= (-1)^{n+1} \binom{-k}{n} g_{k-1}^{(n)}, \end{aligned}$$

where Res_x denotes the residue with respect to the single variable x , and where the coefficients $g_k^{(n)}$ are defined by

$$[g(x)]^n = \sum_{k=0}^{\infty} g_k^{(n)} x^k.$$

We thus finally let

$$\begin{aligned} x(y, z) &= \sum_{\substack{k > 0 \\ n \geq 0}} \frac{(-1)^n}{k} \binom{-k}{n} g_{k-1}^{(n)} (y+z)^k z^n \\ &= y + z + \sum_{\substack{k > 0 \\ n > 0}} \frac{(-1)^n}{k} \binom{-k}{n} g_{k-1}^{(n)} (y+z)^k z^n. \end{aligned} \quad (15)$$

5. Truncation error. In numerical computation, the series (15) will have to be truncated, for instance, by neglecting the terms where $k + n \geq p$ for some positive integer p . We therefore estimate the truncation error

$$t_p(y, z) = \sum_{\substack{k+n=p \\ k>0, n>0}} \frac{(-1)^n}{k} \binom{-k}{n} g_{k-1}^{(n)}(y+z)^k z^n.$$

From (6), the coefficients a_n in

$$[h(x)]^{-1} = \sum_{n=0}^{\infty} a_n x^n$$

are easily seen to satisfy $|a_n| \leq 1$. In view of $a_0 = 1$ we therefore have for $|x| \leq \rho$, $\rho < 1$,

$$|[h(x)]^{-1}| \geq 1 - \rho - \rho^2 - \dots = (1 - 2\rho)/(1 - \rho),$$

and thus, if $0 \leq \rho < \frac{1}{2}$,

$$|h(x)| \leq (1 - \rho)/(1 - 2\rho).$$

Using the principle of the maximum, there follows for $|x| \leq \rho < \frac{1}{2}$,

$$|g(x)| \leq \left| \frac{1}{\rho} \left(\frac{1 - \rho}{1 - 2\rho} - 1 \right) \right| = \frac{1}{1 - 2\rho}.$$

Cauchy's estimate now yields

$$|g_k^{(n)}| \leq \frac{1}{(1 - 2\rho)^n} \frac{1}{\rho^k}, \quad 0 < \rho < \frac{1}{2}.$$

Now let $|y + z| \leq \rho_1$, $|z| \leq \rho_2$. In view of

$$\frac{(-1)^n}{k} \binom{-k}{n} = \frac{1}{k} \binom{k+n-1}{n} = \frac{1}{k+n} \binom{k+n}{n},$$

there follows

$$\begin{aligned} \left| \sum_{\substack{k+n=q \\ k>0, n>0}} \frac{(-1)^n}{k} \binom{-k}{n} g_{k-1}^{(n)}(y+z)^k z^n \right| &\leq \frac{1}{q} \sum_{k+n=q} \binom{q}{n} (1 - 2\rho)^{-n} \rho^{-k+1} \rho_1^k \rho_2^n \\ &= \frac{\rho}{q} \left(\frac{\rho_2}{1 - 2\rho} + \frac{\rho_1}{\rho} \right)^q. \end{aligned}$$

Therefore, if

$$\sigma = \frac{\rho_2}{1 - 2\rho} + \frac{\rho_1}{\rho} < 1, \quad (16)$$

we find the truncation error estimate

$$|t_p(y, z)| \leq \frac{\rho}{p} \frac{\sigma^p}{1 - \sigma}. \quad (17)$$

Choosing, for instance, $\rho = \frac{1}{3}$,

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6. Numerical values. It ren
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of the series (15) in rational a
these values are available from
are required to write the terms

$$h(x) =$$

$$g(x) =$$

$$[g(x)]^2 =$$

$$[g(x)]^3 =$$

This results in

$$x(y, z) = (y \cdot$$

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From the values of the paramet

$$y = 3.2478$$

Substituting these into (19) we

with a truncation error $t_5(y, z)$

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and which thus is less than the

Choosing, for instance, $\rho = \frac{1}{3}$, there results the simple formula

$$|t_p(y, z)| \leq \frac{1}{3^p} \frac{(3\rho_1 + 3\rho_2)^p}{1 - (3\rho_1 + 3\rho_2)}. \quad (18)$$

6. Numerical values. It remains to compute the coefficients $g_k^{(n)}$. This is a routine computation which is best performed with a symbolic manipulator. Using the MAPLE program of the University of Waterloo [2] we computed the $g_k^{(n)}$ as well as the coefficients

$$a_k^{(n)} = \frac{(-1)^n}{k} \binom{-k}{n} g_k^{(n)}$$

of the series (15) in rational arithmetic for $1 \leq k \leq 10$, $1 \leq n \leq 10$. Complete tables of these values are available from the authors on request. Here we give only the values that are required to write the terms of the series for $k + n < 5$:

$$\begin{aligned} h(x) &= 1 - \frac{9}{14}x - \frac{13}{392}x^2 - \frac{4189}{181104}x^3 - \dots, \\ g(x) &= -\frac{9}{14} - \frac{13}{392}x - \frac{4189}{181104}x^2 - \dots, \\ [g(x)]^2 &= \frac{81}{196} + \frac{117}{2744}x + \dots, \\ [g(x)]^3 &= -\frac{729}{2744} - \dots. \end{aligned}$$

This results in

$$\begin{aligned} x(y, z) &= (y + z) \left\{ 1 - \frac{9}{14}z + \frac{81}{196}z^2 - \frac{729}{2744}z^3 + \dots \right\} \\ &\quad + (y + z)^2 \left\{ -\frac{13}{392}z + \frac{351}{5488}z^2 + \dots \right\} \\ &\quad + (y + z)^3 \left\{ -\frac{4189}{181104}z + \dots \right\} \\ &\quad + \dots. \end{aligned} \quad (19)$$

From the values of the parameters given in [1] we have

$$y = 3.247890 \times 10^{-3}, \quad z = 3.461391 \times 10^{-3}.$$

Substituting these into (19) we get

$$x = 6.694379 \times 10^{-3}$$

with a truncation error $t_5(y, z)$, which by (18) is less than

$$\frac{1}{15} \frac{[3 \times 6.709281 \times 10^{-3}]^5}{0.979872} = 2.25 \times 10^{-10},$$

and which thus is less than the error in x due to rounding or measuring errors in y and z .

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RESPONSE BOUNDS F

The behavior of many engine
 equation

where $\tilde{G}(t)$ is a specified oscillation
 respect to t , $F(U)$ is a nonlinear function
 shown in Fig. 1, and $U(0) = \dot{U}(0)$

where $f = \sup|F(U)|$, $u = \sup|U|$

where A is the area of the hysteresis loop