

Math 307  
Spring 2019  
Final - Practice

Name (Print):

Solutions

Time Limit: 120 Minutes

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Problem	Points	Score
1	80	
2	10	
3	10	
4	10	
5	15	
6	20	
7	50	
8	15	
9	20	
10	10	
11	10	
12	10	
13	10	
14	10	
15	20	
Total:	300	

1. (60 points) Answer true or false to the following statements:

If  $V$  is a vector space of dimension  $n$ , then  $V$  is an  $n \times n$  matrix.

False

If 0 is an eigenvalue of  $A$ , then  $A$  is not invertible.

True

If  $V$  is a vector space of dimension  $n$ , then any set of  $n$  vectors must be linearly independent.

False

If  $\det(A) \neq 0$  then  $A$  is invertible.

True

If  $A$  is an  $n \times n$  invertible matrix, then the rows of  $A$  are linearly independent

True

$\det(A + B) = \det(A) + \det(B)$

False

$\det(AB) = \det(A) \det(B)$

True

If  $T$  is a linear transformation, then so is  $T + T^2$ .

True

If  $A$  is invertible and  $B$  is invertible then  $A + B$  is invertible.

False

If  $v_1$  and  $v_2$  are linearly independent then there exists nonzero constants,  $c_1$  and  $c_2$ , such that  $c_1 v_1 + c_2 v_2 = 0$ .

False

If  $\lambda$  is an eigenvalue of  $A$  then  $\det(\lambda I - A) = 0$ .

True

If  $V$  is a vector space of dimension  $n$ , then any collection of  $n$  vectors forms a basis for  $V$ .

False

If  $A$  is an  $n \times n$  matrix with  $n$  distinct eigenvalues, then  $A$  is diagonalizable.

True

If  $A$  is an  $n \times n$  matrix with  $n$  distinct eigenvalues, then  $A$  is invertible.

False

If  $A$  is an  $n \times n$  matrix that is invertible, then  $A$  is diagonalizable.

False

If  $A$  is an  $n \times n$  matrix that is diagonalizable, then  $A$  is invertible.

False

- (a) (10 points) Give a basis for the null space  $NS(A)$  and the column space  $CS(A)$  of the following matrix

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 2 & -1 & 3 \\ -1 & 2 & -2 \end{bmatrix}$$

$NS(A)$ : The  $rref(A)$  is  $\begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & -1/3 \\ 0 & 0 & 0 \end{bmatrix}$ , so, any vector in  $NS(A)$  is of the form  $t \begin{bmatrix} -4/3 \\ 1/3 \\ 1 \end{bmatrix}$ , for some  $t$ , i.e.  $\begin{bmatrix} -4/3 \\ 1/3 \\ 1 \end{bmatrix}$  forms a basis for  $NS(A)$ .

$CS(A)$ : The  $rref(A^T)$  is  $\begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{bmatrix}$ , and so  $(rref(A^T))^T$  is  $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & -1 & 0 \end{bmatrix}$ .  
Hence,  $\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$  and  $\begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix}$  form a basis for  $CS(A)$ .

- (b) (10 points) Solve the following linear system

$$\begin{aligned} x + y + z &= 0 \\ 2x - y + 3z &= 1 \\ -x + 2y - 2z &= -1 \end{aligned}$$

One way to do this using the first part of the problem is

① Find one solution, say  $(x_0, y_0, z_0)$ , to the system

② All solutions will be of the form  $(x_0, y_0, z_0) + NS(A)$ .

To find one solution, set  $z=0$  and see that  $(1/3, -1/3, 0)$  gives a solution.

$$\text{so, } \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 1/3 \\ -1/3 \\ 0 \end{bmatrix} + t \begin{bmatrix} -4/3 \\ 1/3 \\ 1 \end{bmatrix} \quad \text{for } t \in \mathbb{R}$$

gives all solutions to the system.

2. (10 points) Consider the matrix

$$\begin{bmatrix} 2 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 3 \end{bmatrix}$$

Determine  $\dim(E_1)$ ,  $\dim(E_2)$  and  $\dim(E_3)$ .

$\begin{matrix} \parallel & \parallel & \parallel \\ 2 & 1 & 1 \end{matrix}$

3. (10 points) Determine which of the following matrices are similar to the matrix

$$\begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 3 \end{bmatrix}$$

YES      NO ← NOT in JNF, but it's easy to check that this is diagonalizable!

$\begin{bmatrix} 1 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 3 \end{bmatrix}$	$\begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 3 \end{bmatrix}$	$\begin{bmatrix} 3 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$	$\begin{bmatrix} 1 & 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 3 \end{bmatrix}$	$\begin{bmatrix} 1 & 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 3 \end{bmatrix}$
YES	NO	YES	NO	NO

4. (10 points) Suppose that the characteristic polynomial of  $A$  is  $(\lambda - 1)^4(\lambda - 2)^3$ . If  $\dim(E_1) = 2$  and  $\dim(E_2) = 1$ , give the possible (up to permutation) Jordan Normal Forms of  $A$ .

The JNF of  $A$  is  $\begin{bmatrix} B_1 & 0 \\ 0 & B_2 \end{bmatrix}$  where

$B_1 = \begin{pmatrix} 2 & 1 & 0 \\ 0 & 2 & 1 \\ 0 & 0 & 2 \end{pmatrix}$ 
 and  $B_2 = \begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{pmatrix}$ 
 OR

$B_2 = \begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$

5. Consider the homogeneous first order linear differential system

$$\begin{aligned}x' &= x - y + z \\y' &= 2y + z \\z' &= 2z\end{aligned}$$

where  $x, y, z$  are all functions of the variable  $t$ .

(a) (5 points) Write the system in the matrix form  $Y' = AY + G$ .

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix}' = \begin{bmatrix} 1 & -1 & 1 \\ 0 & 2 & 1 \\ 0 & 0 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

(b) (5 points) Is the matrix  $A$  diagonalizable? Explain your answer.

The eigenvalues of  $A$  are 1 and 2. Notice that

$$2I - A = \begin{bmatrix} 1 & 1 & -1 \\ 0 & 0 & -1 \\ 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}, \text{ so } \dim(E_2) = 1, \therefore A \text{ is not diagonalizable.}$$

(c) (5 points) Find the general solution to the homogeneous system  $Y' = AY$ .

Firstly,  $z = c_3 e^{2t}$ . Next,  $y' = 2y + e^{2t} \Rightarrow \frac{d}{dt}(ye^{-2t}) = c_3$ .

So,  $y = c_2 e^{2t} + c_3 t e^{2t}$ . Further,

~~$(e^{-t} x)' = x - (c_2 e^{2t} + c_3 t e^{2t}) + c_3 e^{2t}$  which gives~~

$$x' = x - (c_2 e^{2t} + c_3 t e^{2t}) + c_3 e^{2t}, \text{ so,}$$

$$\frac{d}{dt}(x e^{-t}) = -c_2 e^t - c_3 t e^t + c_3 e^t \text{ and whence}$$

$$x = c_1 e^t + (-c_2 + 2c_3 - c_3 t) e^{2t}.$$

6. (20 points) Solve the initial value problem

$$Y' = \underbrace{\begin{bmatrix} 2 & 1 \\ -1 & 2 \end{bmatrix}}_A Y + \underbrace{\begin{bmatrix} e^x \\ 0 \end{bmatrix}}_G, \quad Y(0) = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

The eigenpairs of  $A$  are  $(2+i, \begin{bmatrix} -i \\ 1 \end{bmatrix})$  and  $(2-i, \begin{bmatrix} i \\ 1 \end{bmatrix})$ . As such, if  $P = \begin{bmatrix} -i & i \\ 1 & 1 \end{bmatrix}$ , then  $P^{-1}AP = \begin{bmatrix} 2+i & 0 \\ 0 & 2-i \end{bmatrix}$ , and we see that  $\begin{bmatrix} e^{(2+i)x} \\ 0 \end{bmatrix}$  is a solution to

$$\varphi' = D\varphi. \quad \text{Since } e^{(2+i)x} = e^{2x}(\cos(x) + i\sin(x)), \quad P \begin{bmatrix} e^{(2+i)x} \\ 0 \end{bmatrix} = \underbrace{\begin{bmatrix} e^{2x}\sin(x) \\ e^{2x}\cos(x) \end{bmatrix}}_{\varphi_1} + i \underbrace{\begin{bmatrix} -e^{2x}\cos(x) \\ e^{2x}\sin(x) \end{bmatrix}}_{\varphi_2}.$$

This gives our matrix of solutions to  $\varphi' = A\varphi$  to be

$$M = \begin{bmatrix} e^{2x}\sin(x) & -e^{2x}\cos(x) \\ e^{2x}\cos(x) & e^{2x}\sin(x) \end{bmatrix} \quad \text{and, so,} \quad M^{-1} = \begin{bmatrix} e^{-2x}\sin(x) & e^{-2x}\cos(x) \\ -e^{-2x}\cos(x) & e^{-2x}\sin(x) \end{bmatrix}.$$

We have  $M^{-1}G = \begin{bmatrix} e^{-x}\sin(x) \\ -e^{-x}\cos(x) \end{bmatrix}$  and so  $\int M^{-1}G = \begin{bmatrix} -\frac{e^{-x}}{2}\sin(x) + \frac{e^{-x}}{2}\cos(x) \\ \frac{e^{-x}}{2}\cos(x) - \frac{e^{-x}}{2}\sin(x) \end{bmatrix}$

This gives  $\underbrace{M \int M^{-1}G}_{\varphi_p} = \begin{bmatrix} -e^x/2 \\ -e^x/2 \end{bmatrix}$ . ~~Adding  $\varphi_1$  and  $\varphi_2$~~

So, our solution to  $\varphi' = A\varphi + G$  is  $c_1\varphi_1 + c_2\varphi_2 + \varphi_p$ .

IVP:  $\begin{bmatrix} 1 \\ 1 \end{bmatrix} = \varphi(0) = \begin{bmatrix} -c_2 \\ c_1 \end{bmatrix} + \begin{bmatrix} -1/2 \\ -1/2 \end{bmatrix} \quad \therefore c_1 = 3/2, \quad c_2 = -3/2.$

So, the solution to the IVP is

$$\varphi = \frac{3}{2}\varphi_1 - \frac{3}{2}\varphi_2 + \varphi_p.$$

7. Let's consider the non-homogeneous first order linear differential system

$$\begin{aligned}x' &= -4x - 3y + 3z \\y' &= 3x + 2y - 3z + e^t \\z' &= -3x - 3y + 2z\end{aligned}$$

where  $x, y, z$  are all functions of the variable  $t$ .

(a) (5 points) Write the system in the matrix form  $Y' = AY + G$ .

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix}' = \begin{bmatrix} -4 & -3 & 3 \\ 3 & 2 & -3 \\ -3 & -3 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} + \begin{bmatrix} 0 \\ e^t \\ 0 \end{bmatrix}$$

(b) (15 points) Find a diagonal matrix  $D$  and an invertible matrix  $P$  such that  $D = P^{-1}AP$ .

One finds  $p(\lambda) = (\lambda + 1)^2 (\lambda - 2)$  (make sure you can do this by hand!)

$$\lambda = -1 \quad -1 - A = \begin{bmatrix} +3 & +3 & -3 \\ -3 & -3 & +3 \\ 3 & 3 & -3 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & -1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \therefore \text{eigenvectors } \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

$$\lambda = 2 \quad 2 - A = \begin{bmatrix} 6 & 3 & -3 \\ -3 & 0 & 3 \\ 3 & 3 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} \therefore \text{eigenvector } \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$$

$$P = \begin{bmatrix} 1 & 1 & 1 \\ -1 & 0 & -1 \\ 0 & 1 & 1 \end{bmatrix}, \quad D = \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 2 \end{bmatrix}$$

(c) (5 points) Find the general solution to the homogeneous system  $Z' = DZ$ .

$$Y_{H,D} = \begin{bmatrix} c_1 e^{-t} \\ c_2 e^{-t} \\ c_3 e^{2t} \end{bmatrix}$$

(d) (5 points) Use the result of the previous question to find the general solution  $Y_H$  to the homogeneous system  $Y' = AY$ , and find a fundamental set,  $Y_1, Y_2, Y_3$ , of solutions to this system.

$$Y_{H,A} = P Y_{H,D} = \begin{bmatrix} 1 & 1 & 1 \\ -1 & 0 & -1 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} c_1 e^{-t} \\ c_2 e^{-t} \\ c_3 e^{2t} \end{bmatrix}$$

$$= \begin{bmatrix} c_1 e^{-t} + c_2 e^{-t} + c_3 e^{2t} \\ -c_1 e^{-t} - c_3 e^{2t} \\ c_2 e^{-t} + c_3 e^{2t} \end{bmatrix}$$

$$= c_1 \underbrace{\begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}}_{Y_1} e^{-t} + c_2 \underbrace{\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}}_{Y_2} e^{-t} + c_3 \underbrace{\begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}}_{Y_3} e^{2t}$$



- (e) (15 points) Using the matrix  $M = [Y_1 \ Y_2 \ Y_3]$ , compute a particular solution  $Y_p$  to the non-homogeneous system  $Y' = AY + G$ .

$$M = \begin{bmatrix} e^{-t} & e^{-t} & e^{2t} \\ -e^{-t} & 0 & -e^{2t} \\ 0 & e^{-t} & e^{2t} \end{bmatrix} \quad \text{one finds} \quad M^{-1} = \begin{bmatrix} e^t & 0 & -e^t \\ e^t & e^t & 0 \\ -e^{2t} & -e^{2t} & e^{-2t} \end{bmatrix},$$

$$\text{Now, } M^{-1}G = \begin{bmatrix} 0 \\ e^{2t} \\ -e^{-t} \end{bmatrix} \Rightarrow \int M^{-1}G = \begin{bmatrix} 0 \\ \frac{1}{2}e^{2t} \\ e^{-t} \end{bmatrix}$$

$$\text{and hence, } \underbrace{M \int M^{-1}G}_{Y_p} = \begin{bmatrix} \frac{3}{2}e^t \\ -e^t \\ \frac{3}{2}e^t \end{bmatrix}$$

- (f) (5 points) Use the result of the previous question to find the general solution to the non-homogeneous system  $Y' = AY + G$ .

The general solution to is

$$\underbrace{\quad}_{Y_{H,A}} + \underbrace{\quad}_{Y_p} \quad ! \quad ! \quad !$$

8. Consider the following system:

$$\begin{aligned}y_1'' &= y_1' + y_2' + e^x \\ y_2'' &= y_1 + y_2 + \sin(x)\end{aligned}$$

where  $y_1$  and  $y_2$  are functions of  $x$ .

(a) (10 points) Write this system as a system of first order linear differential equations in the form  $Y' = AY + G$ .

$$\begin{array}{l} \text{Let } v_1 = y_1 \\ v_2 = y_1' \\ v_3 = y_2 \\ v_4 = y_2' \end{array} \quad \begin{array}{l} \text{Now, } v_1' = v_2 \\ v_2' = v_2 + v_3 + e^x \\ v_3' = v_4 \\ v_4' = v_1 + v_3 + \sin(x) \end{array}$$

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{bmatrix}' = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 1 & 0 \end{bmatrix}$$

(b) (5 points) Give a condition on  $A$  so that we can solve this system with the techniques learned in this class.

If  $A$  is diagonalizable, then we can solve this system!

9. (a) (5 points) Write the following differential equation as a system of first order linear equations:

$$y'' + 4y' + 3y = 0$$

$$\begin{aligned} V_1 &= y \\ V_2 &= y' \end{aligned} \quad \therefore \begin{bmatrix} V_1 \\ V_2 \end{bmatrix}' = \underbrace{\begin{bmatrix} 0 & 1 \\ -3 & -4 \end{bmatrix}}_A \begin{bmatrix} V_1 \\ V_2 \end{bmatrix}.$$

$$V_1' = V_2$$

$$V_2' = -3V_1 - 4V_2$$

- (b) (10 points) Solve the system from part a).

One finds the eigenvalues of  $A$  to be  $-3$  and  $-1$ .

$$-1 - A = \begin{bmatrix} -1 & -1 \\ 3 & 3 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} \text{ eigen vector } \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

$$-3 - A = \begin{bmatrix} -3 & -1 \\ 3 & 1 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & 1/3 \\ 0 & 0 \end{bmatrix} \text{ eigenvector } \begin{bmatrix} -1/3 \\ 1 \end{bmatrix}.$$

$$\mathcal{Y}_H = \begin{bmatrix} -1 & -1/3 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} c_1 e^{-x} \\ c_2 e^{-3x} \end{bmatrix} = \begin{bmatrix} -c_1 e^{-x} - \frac{1}{3} c_2 e^{-3x} \\ c_1 e^{-x} + c_2 e^{-3x} \end{bmatrix}$$

- (c) (5 points) Verify your solution by computing the kernel of the appropriate differential operator.

From  $\mathcal{Y}_H$  we see that  $y = V_1 = -c_1 e^{-x} - \frac{1}{3} c_2 e^{-3x}$

... But also, if ~~the~~  $D^2 + 4D + 3$  is our operator, then we know that

$y = e^{-3x}$  and  $y = e^{-x}$  form a basis for the kernel!

10. (10 points) Let be  $A$  an  $n \times n$  matrix, prove that  $\text{Rank}(A) = n$  if and only if  $A$  is invertible.

The proofs are all  
on old practice tests.