

16.5

#6.

$$(a) \operatorname{curl} \vec{F} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ D_x & D_y & D_z \\ \tan^{-1}(xy) & \tan^{-1}(yz) & \tan^{-1}(zx) \end{vmatrix}$$

$$= \vec{i} \left(0 - \frac{y}{(yz)^2 + 1} \right) - \vec{j} \left(\frac{z}{(zx)^2 + 1} - 0 \right) + \vec{k} \left(0 - \frac{x}{(xy)^2 + 1} \right)$$

$$= -\frac{y}{(yz)^2 + 1} \vec{i} - \frac{z}{(zx)^2 + 1} \vec{j} - \frac{x}{(xy)^2 + 1} \vec{k}$$

$$(b) \operatorname{div} \vec{F} = \frac{y}{(xy)^2 + 1} + \frac{z}{(yz)^2 + 1} + \frac{x}{(zx)^2 + 1}$$

#12.

v.f - vector field
s.f - scalar field

(a) $\text{curl } f$ nonsense

(b) $\text{grad } f$ v.f.

(c) $\text{div } \vec{F}$ s.f.

(d) $\text{curl}(\text{grad } f)$ v.f.

(e) $\text{grad } \vec{F}$ nonsense

(f) $\text{grad}(\text{div } \vec{F})$ v.f.

(g) $\text{div}(\text{grad } f)$ s.f.

(h) $\text{grad}(\text{div } f)$ nonsense

(i) $\text{curl}(\text{curl } \vec{F})$ v.f.

(j) $\text{div}(\text{div } \vec{F})$ nonsense

(k) $\text{grad } f \times \text{div } \vec{F}$ nonsense

(l) $\text{div}(\text{curl}(\text{grad } f))$ s.f.

#26. $\vec{F} = \langle P, Q, R \rangle$

$$\text{curl}(\vec{F}) = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ P_x & Q_x & R_x \\ P_y & Q_y & R_y \end{vmatrix}$$

$$= \vec{i} \left[\underline{P_y R} + \underline{P_y R_y} - (\underline{P_z Q} + \underline{P_z Q_z}) \right]$$

$$- \vec{j} \left[\underline{P_x R} + \underline{P_x R_x} - (\underline{P_z P} + \underline{P_z P_z}) \right]$$

$$+ \vec{k} \left[\underline{P_x Q} + \underline{P_x Q_x} - (\underline{P_y P} + \underline{P_y P_y}) \right]$$

$$= \frac{(P_y R - P_z Q) \vec{i} - \vec{j} (P_x R - P_z P)}{\quad}$$

$$+ \frac{(P_x Q - P_y P) \vec{k}}{\quad}$$

$$+ \frac{\vec{i} (P_y R - P_z Q) - \vec{j} (P_x R - P_z P)}{\quad}$$

$$+ \frac{\vec{k} (P_x Q - P_y P)}{\quad}$$

$$= f \left[\vec{i}(P_y - Q_z) - \vec{j}(P_x - P_z) + \vec{k}(Q_x - P_y) \right]$$

$$+ \vec{i}(f_y R - f_z Q) - \vec{j}(f_x R - f_z P) + \vec{k}(f_x Q - f_y P)$$

$$= f \cdot \text{curl}(\vec{F}) + \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ f_x & f_y & f_z \\ P & Q & R \end{vmatrix}$$

$$= f \cdot \text{curl}(\vec{F}) + (\nabla f) \times \vec{F}$$