

Math 411
Solutions to Asst 13

(1)(a) if $\alpha_1 = 0$, then $\alpha_1 I - A = \begin{pmatrix} 0 & 0 & 0 \\ -1 & 0 & \alpha_2 \alpha_3 \\ 0 & -1 & -\alpha_2 - \alpha_3 \end{pmatrix}$

which has 2 pivots independent of the values of α_2 & α_3 , so $\dim \ker(\alpha_1 I - A) = 1$.

Since $\alpha_1, \alpha_2, \alpha_3$ are arbitrarily labelled, the same is true if you assume $\alpha_2 = 0$

(b) let $\alpha_i, \alpha_j, \alpha_k$ be the three roots

or $\alpha_3 = 0$. QED

Then $\alpha_i I - A = \begin{pmatrix} \alpha_i & 0 & -\alpha_i \alpha_j \alpha_k \\ -1 & \alpha_i & \alpha_i \alpha_j + \alpha_i \alpha_k + \alpha_j \alpha_k \\ 0 & -1 & -\alpha_j - \alpha_k \end{pmatrix} \rightsquigarrow \begin{pmatrix} -1 & \alpha_i & \alpha_i \alpha_j + \alpha_i \alpha_k + \alpha_j \alpha_k \\ 0 & -1 & -\alpha_j - \alpha_k \\ 0 & \alpha_i^2 & \alpha_i^2 \alpha_j + \alpha_i^2 \alpha_k \end{pmatrix}$

$-\alpha_i R_2 = \alpha_i \quad -\alpha_i^2 \quad -\alpha_i^2 \alpha_j - \alpha_i^2 \alpha_k - \alpha_j \alpha_k \alpha_i$
 $R_1 = \alpha_i \quad 0 \quad -\alpha_i \alpha_j \alpha_k$

$\begin{pmatrix} -1 & \alpha_i & \alpha_i \alpha_j + \alpha_i \alpha_k + \alpha_j \alpha_k \\ 0 & -1 & -\alpha_j - \alpha_k \\ 0 & 0 & 0 \end{pmatrix}$

so $\dim \ker = 1$

(2)(a) $xI - A$ is diagonal, $n \times n$, with diagonal entries $x - \lambda$, so $\det = (x - \lambda)^n$. QED

(b) $\lambda I - A = \begin{pmatrix} 0 & \ominus \\ 0 & 0 & \ominus \\ 0 & 0 & 0 & \ominus \\ \dots & \dots & \dots & \ominus \\ 0 & 0 & 0 & 0 & \ominus \end{pmatrix}$

so $n-1$ pivots so $\dim \ker = 1$ QED

(3) Claim 1: If $A = \begin{pmatrix} A_1 & 0 \\ 0 & I_{n_2} \end{pmatrix}$, where I_{n_2} is $n_2 \times n_2$ identity matrix, then $\det(A) = \det(A_1)$

~~proof: induction on n_2 : if $n_2 = 1$, $\det(A) = \det(A_1)$~~

4 If $A = \begin{pmatrix} I_{n_1} & 0 \\ 0 & A_2 \end{pmatrix}$ then $\det A = \det A_2$.

proof: first: $A = \begin{pmatrix} I_{n_1} & 0 \\ 0 & A_2 \end{pmatrix}$: induction on n_1 : if $n_1 = 1$, $\det(A) = \begin{vmatrix} 1 & 0 \\ 0 & A_2 \end{vmatrix} = 1 \cdot \det(A_2)$ ✓

for $n_1 > 1$: view A as $\begin{pmatrix} I_{n_1} & 0 \\ 0 & A_2 \end{pmatrix}$ as $\begin{pmatrix} 1 & 0 \\ 0 & A_2' \end{pmatrix}$

where $A_2' = \begin{pmatrix} I_{n_1-1} & 0 \\ 0 & A_2 \end{pmatrix}$. Then as in $n_1 = 1$ case, $\det(A) = \det(A_2')$ 4 by ind. hypothesis $\det(A_2') = \det(A_2)$

(3) for $A = \left(\begin{array}{c|c} A_1 & 0 \\ \hline 0 & I_{n_2} \end{array} \right)$, do the same thing. QED

Claim 2: suppose $A = \left(\begin{array}{c|c} A_1 & 0 \\ \hline 0 & A_2 \end{array} \right)$, then $\det(A) = \det(A_1) \det(A_2)$

proof: note $A = \underbrace{\left(\begin{array}{c|c} A_1 & 0 \\ \hline 0 & I_{n_2} \end{array} \right)}_{A'} \underbrace{\left(\begin{array}{c|c} I_{n_1} & 0 \\ \hline 0 & A_2 \end{array} \right)}_{A''}$

Then $\det(A) = \det(A') \det(A'') = \det(A_1) \det(A_2)$
 by Claim 1 QED

Claim 3: if $A = \bigoplus_{i=1}^k A_i$, then $\det(A) = \prod_{i=1}^k \det(A_i)$

proof: induction on k : $k=2$ is claim 2

suppose true for $k-1$ blocks. $A = A_1 \oplus A_2'$ where $A_2' = \bigoplus_{i=2}^k A_i$

by claim 2, $\det(A) = \det(A_1) \det(A_2')$

by ind. hypothesis, $\det(A_2') = \prod_{i=2}^k \det(A_i)$ QED.

(4)(a) let $W = \mathbb{R}^{n+1}$ & let $\varphi: V \xrightarrow{\sim} W$ given by $\varphi(x^i) = e_{i+1}$, i.e. the "coordinates with respect to $B = \{1, x, x^2, \dots, x^n\}$ " isomorphism. $\frac{d}{dx} x^i = i x^{i-1}$ so

Then $\left[\frac{d}{dx} \right]_B = \begin{pmatrix} 0 & 1 & & & \\ & 0 & 2 & & \\ & & 0 & 3 & \\ & & & 0 & \ddots \\ 0 & & & & 0 & n \\ & & & & & & 0 \end{pmatrix}$ so $\det\left(\frac{d}{dx}\right) = \det\left(\left[\frac{d}{dx} \right]_B\right) = 0$

~~part~~

(c) $\text{char}_{\frac{d}{dx}}(t) = \det\left(\begin{matrix} t \cdot I & \\ & -\left[\frac{d}{dx} \right]_B \end{matrix}\right) = \begin{vmatrix} t-1 & & & \\ & t-2 & & \\ & & \ddots & \\ & & & t-n \\ & & & & t \end{vmatrix} = t^{n+1}$

(b) by (c), $\lambda=0$ is the only e-value. Then $\text{ker} \det\left(\frac{d}{dx} - 0\right) = \varphi^{-1}(\text{Null}\left(\left[\frac{d}{dx} \right]_B - 0\right))$
 & $\text{Null}\left(\left[\frac{d}{dx} \right]_B\right)$ is 1-dim'd with basis $\left\{ \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix} \right\}$. so $\mathcal{L} = \varphi^{-1}(\text{Span}\left(\begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}\right)) = \text{constants}$
 QED

$$(5) (a) A_1 - 2 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = 0, \quad A_2 - 2 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} \neq 0, \quad A_3 - 2 = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} \neq 0$$

$$(A_2 - 2)^2 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = 0 \quad (A_3 - 2)^2 = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \neq 0$$

$$(A_3 - 2)^3 = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = 0 \quad \text{QED}$$

(b) From we see that there are 0, 1, & 2 pivots so $\dim \ker$ is 3, 2, 1, respectively.

(c) A is diagonalizable iff there's a basis of e-vectors. since $\ker(A_1 - 2) = F^3$, there's a basis of F^3 consisting of e-vectors of A_1 , so A_1 is diagonalizable.

$$\text{Char}_{A_2}(x) = \begin{vmatrix} x-2 & 0 & 0 \\ 0 & x-2 & -1 \\ 0 & 0 & x-2 \end{vmatrix} = (x-2)^3 \quad \& \quad \text{Char}_{A_3}(x) = \begin{vmatrix} x-2 & -1 & 0 \\ 0 & x-2 & -1 \\ 0 & 0 & x-2 \end{vmatrix} = (x-2)^3$$

~~Char~~ so their only e-value is $\lambda=2$. since $\ker(A_i - 2) \subsetneq F^3$ for $i=2,3$, there is no basis of F^3 of e-vectors of A_i , $i=2,3$, so A_i is not diagonalizable for $i=2,3$ QED

(d) $\text{Char}_{A_1}(x) = \begin{vmatrix} x-2 & 0 & 0 \\ 0 & x-2 & 0 \\ 0 & 0 & x-2 \end{vmatrix} = (x-2)^3$. Char_{A_2} & Char_{A_3} were computed above.

(6) (a) Part (a) of (5) says that min. poly of A_i is $f_i(x)$. the min poly

(b) Since min poly divides char poly $= x^{n+1}$ ^{x divides the min poly} we just need to show that $\left(\frac{d}{dx}\right)^j \neq 0$

$\forall 0 \leq j \leq n$. Well, let $v = x^n$. Then $\left(\frac{d}{dx}\right)^j(v) = n(n-1)\dots(n-(j-1))x^{n-j} \neq 0$ QED

~~is~~ T is diagonalizable iff its min poly is a product of distinct linear factors. if $n \geq 1$, then x^{n+1} is not such, so T is not diagonalizable. QED

(7) (a) one could find a matrix for T , but in fact note that $T(x^j) = x \frac{d}{dx} x^j = jx^j$ so

$v_j = x^j$ is an e-vector with e-value $\lambda_j = j$ for $j=0, \dots, n$. Since an operator on an $(n+1)$ -dim'l space has at most $(n+1)$ e-values, & $\lambda_j = j$, $j=0, \dots, n$ is $(n+1)$ (distinct) e-values, these are all the e-values of T

(b) From (a), $\text{Char}_T(x) = \prod_{j=0}^n (x-j)$ (c) since $m_T(x)$ divides $\text{Char}_T(x)$ & the latter is a product of distinct factors, $m_T(x)$ is a prod of distinct linear factors, T is diagonalizable. (d) since $m_T(x)$ is a prod of distinct linear factors, T is diagonalizable. (3)